

Individual and precise

Automatic robot path correctionen
with VMT™ BK



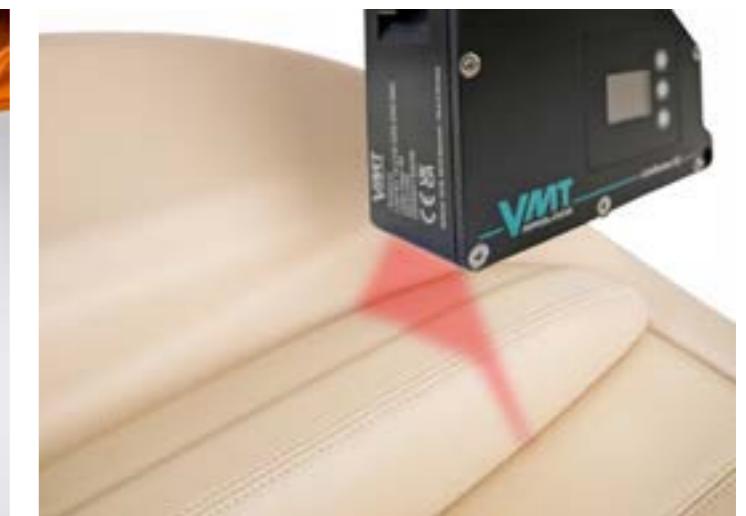
VMT
PEPPERL+FUCHS



Functionality and application possibilities

The VMT™ BK system is an automation process that adapts the nominal path of a robot optimally and individually to the shape/contour of any component.

The process is based on three components developed by VMT™: The LineRunner, a laser triangulation sensor, that generates the measurement value along the processing contour, the technology package to communicate with all current robot controls and the VMT software for evaluation and visualization. Everything from a single source: VMT™.



Advanced automation in different production processes requires an individual processing path that fits the respective component.

VMT™ BK includes the respective component or processing contour and guides the robot along the component in keeping with the data.

VMT™ BK deployment is conceivable for all robot applications in which a processing tool has to be guided on the basis of the respective component geometry.

The different component geometries are achieved by production and assembly processes but can also be created by unstable components.

- Cosmetic joint sealing in vehicle doors and hatches (hemflange

seam sealing)

■ Precise welding applications along sheet overlaps for example

■ Sewing application on leather elements for vehicle interiors or even shoes for example

The application in detail

With the VMT™ BK system for automated path correction, nominal path for robots are corrected and updated with a precision of +/- 0.1 mm.

Path correction is carried out in a two-stage process. In a measurement run, deviations in component position are first measured to a reference component. Finally, a correction is calculated using the VMT software and the nominal path of the robot is optimally calculated so that the available component is aligned. The result is visualized and can be individually aligned within the VMT working scope. Depending on applied laser triangulation sensors, the position and component tolerances can be corrected to a high degree of precision in the range of +/- 15 mm.



Measuring run

During the measuring run, the contour of the component is scanned and compared with the reference component. To do this, the robot's VMT laser triangulation sensor is guided along the processing contour. By means of the measuring points, the current 3D position of the component is determined. With this information, the robot's nominal path is corrected with a precision of +/- 0.1 mm.

During the measuring run, the VMT BK system also checks the nominal path of the robot for potential collision risks present in the processing area. If any are detected, an application run is not allowed.

Application run

The VMT BK system calculates an optimal and individual robot path adapted to the available component and relative to the nominal path. If a collision-free application is possible, the robot administers it so that the component is highly precise and process-safe.

On the robot side, the operation of the system is assumed by a provided technology package. The package does not require any expensive programming and is available for all current robot controls.

System advantages

Flexible and extendable – even in the most demanding applications VMT™ offers individual and optimal solutions. The market-tested automation system ensure high system availability, process safety and system capacity.

Automated determination of tool data

The VMT BK sensor is internally calibrated ex works. The measurement results are therefore given in millimeters. Using a simple, automatable process, it is possible to determine the tool data of the sensor on the robot quickly and precisely. Monitoring sensor TCP data is also possible this way at any time.

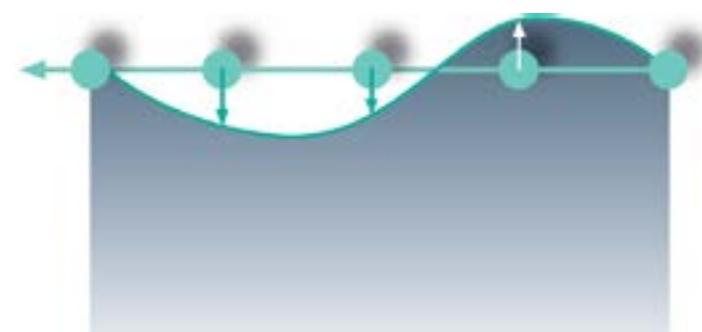


Managing measurement data

The VMT BK system solution seamlessly logs all system activities and measurement values. For long-term data storage it can be connected to a database.

Robust sensor system

The VMT LineRunner laser triangulation sensor works in the infrared range and because of this is robust in varying lighting conditions, surface properties and backgrounds.



System extensions

Additionally, the BK module can be extended with each VMT software module: 3D position detection, 2D position detection, inspection etc.

Application can be optimized when there are form deviations in components

The VMT BK system can be individually aligned to the form and stability of a component. The number of measurement points is scalable and is aligned with the requirements of the component. System scalability allows position correction of the entire component, different areas or even single points.

VMT BK allows safe detection of component edges, sheet overlapping, - in brief, any contour that can be geometrically determined.

LineRunner Sensor family



For challenges in guide correction, edge and slot measurement or inspection tasks, VMT™ has developed a high-performance and secure laser stripe sensor family.

Highlights

- Significant improvement in capture quality at greater distances and on dark surfaces due to the use of Class 2 lasers
- No influence from changing background appearances
- No limitations in choice of measurement location using object geometry
- No influence from changing surface appearances (color quality)
- Only Ethernet and power supply line

In laser stripe processes, a line is projected onto an object, and this line is determined by a camera at a given angle. With the triangulation principle, height and width information can be determined.

The new Generation - VMT LineRunner G2

The LineRunner G2 features a completely newly developed laser module implemented with state-of-the-art technology, offering numerous advantages.

Thanks to the new laser modules, the LineRunner G2 achieves a significantly higher scanning rate of 200 up to 4000 scans per second. The now employed powerful red laser significantly enhances robustness in feature detection, especially on dark surfaces.

Furthermore, the measurement range as well as the lateral resolution in the X direction has been expanded to increase the detection range for features.

For optimized data transmission, a gigabit interface has been integrated.

The second-generation sensor is noticeably more compact in its design and can be positioned, where necessary, to the exact same position as the predecessor through a specially designed mechanical mounting frame.

Technical data OLV 122

General data	Working area Z	65...125mm
	Measurement area	X = 40 mm...58 mm Z = 60 mm
	Laser class	2
Electrical data	Supply voltage	18...30 V
	Current consumption (Ub = 24 V) ¹	350 mA
Interface	Interface type	Ethernet TCP/IP
	Transmission speed	100/1000 MBit/s
Input/Output	Number of I/Os	4
	Voltage Drop	<1,5 V
Switching output	Switching Current	100 mA
	Ambient temperature	0...45 °C (32...113 °F)
Ambient conditions	Storage temperature	-20...70 °C (-4...158 °F)
	Mechanical data	
	Degree of protection	IP65
	Protection class	III

Technical data OLV 250

General data	Working area Z	90...280mm
	Measurement area	X = 62 mm...145 mm Z = 190 mm
	Laser class	2M
Electrical data	Supply voltage	18...30 V
	Current consumption (Ub = 24 V) ¹	300 mA
Interface	Interface type	Ethernet TCP/IP
	Transmission speed	100/1000 MBit/s
Input/Output	Number of I/Os	4
	Voltage Drop	<1,5 V
Switching output	Switching Current	100 mA
	Ambient temperature	0...45 °C (32...113 °F)
Ambient conditions	Storage temperature	-20...70 °C (-4...158 °F)
	Mechanical data	
	Degree of protection	IP67
	Protection class	III

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